

100663600-030102

TITLE: ROTARY SOIL PROBE

BACKGROUND OF THE INVENTION

Soil probes are well known in the art for collecting soil samples. These prior art soil samplers take a variety of forms, including a rotary wheel with a soil probe extending radially outwardly from the perimeter of the wheel. Such rotary probes are typically pulled behind a vehicle such that the probe penetrates the soil near the six o'clock position and then is withdrawn from the soil as the rotation of the wheel continues. Thus, the soil sample is received in the open outer end of the probe. The soil sample then is discharged through the inner end of the probe and deposited in a container positioned within the perimeter of the wheel.

Such prior art rotary soil probes have several shortcomings. For example, the soil samples occasionally become compacted in the probes and do not discharge through the inner end into the compartment. Also, the samples cannot be easily removed from the compartment without stopping the wheel. Also, the wheel is relatively large in diameter such that its size presents a hazard when transporting the wheel down a roadway, since the wheel extends substantially behind the rear of the vehicle upon which it is mounted.

Also, conventional rotary soil probes are relatively slow. For example, one known rotary probe covers approximately 80 acres per hour.

Therefore, a primary objective of the present invention is the provision of an improved rotary soil probe.

Another objective of the present invention is the provision of a rotary soil probe wheel having a plurality of

1008867000-0001002

wheel and a rod pivotally mounted on the arm. A cam surface engages the arm as the wheel turns to move the rod from an retracted to an extended position with respect to the probe. As the rod is extended into the probe, the soil sample received in the outer end of the probe is discharged through the outer end for collection. Thus, the rotary soil probe of the present invention can be operated continuously without stopping to collect the soil samples.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a rear perspective view of the rotary soil probe of the present invention mounted on the back of a pickup truck.

Figure 2 is a side elevation view from one side of the soil probe.

Figure 3 is a side elevation view from the opposite side of the soil probe.

Figure 4 is a perspective view showing the soil probe folded to the transport position.

Figure 5 is a perspective view showing the inside of the wheel, the plunger assembly and an anti-reverse mechanism.

DETAILED DESCRIPTION OF THE INVENTION

The rotary soil probe of the present invention is generally designated by the reference numeral 10 in the drawings. The probe 10 includes a frame 12 adapted to be mounted on the back of a vehicle, such as a pickup truck 14, and a wheel 16 rotatably mounted on the frame 12. The wheel 16 includes a plurality of probes 18 adapted to pull soil samples from the soil as the truck moves forwardly to rotate the wheel over the soil. The probes each have a beveled outer end and at least one axially extending slot 19 to

facilitate collection and discharge of soil to and from the probe 18.

More particularly, the frame 12 of the soil probe 10 includes a first section 20 mounted to the truck for pivotal movement about a horizontal axis, and a second section 22 pivotally connected to the first section 20 for movement about a substantially vertical axis. The first frame section 20 includes an elongated member preferably mounted on the rear bumper of the truck 14 so as to be horizontally disposed, with the longitudinal axis of the member 20 defining the horizontal pivot axis for the first frame section 20. A leg 20 extends downwardly from the member 24 and is connected to the extensible rod 28 of a hydraulic cylinder 30. The cylinder 30 is mounted to the frame of the truck 14 and is operatively connected to a hydraulic fluid source (not shown). The controls for the hydraulic cylinder 30 are preferably located in the bed of the truck 14 so that an assistant riding in the back of the truck can operate the cylinder 30.

A yoke 32, defined by a pair of spaced apart arms, extends rearwardly from the elongated member 24. The inner end of the second frame section 22 extends between the plates of the yoke 32 and is pivotally connected thereto by a bolt 34. The bolt 34 defines a substantially vertical or upwardly angled pivot axis about which the second frame section 22 pivots relative to the first frame section 20, such that the second frame section 22 is moveable between a rearwardly extending use position, shown in Figures 1-3, and a laterally extending folded or transport position, shown in Figure 4. The inner terminal end of the second frame section 22 includes a hole adapted to receive a lock pin 36 extending through aligned slots 38 in the plates of the yoke 32. The pin 36 retains the second frame section 22 and the attached

10086360-030102

wheel 16 in the extended use position, while the slots 38 allow an angle of play, preferably 10° - 15° , in the alignment of the first frame section 20 and the yoke 32, so as to prevent binding of the wheel 16 if the truck 14 deviates slightly from a straight line path. In the folded transport position, the weight of the wheel 16 and the angled axis of bolt 34 keeps the soil probe 10 in the transport position.

The outer end of the second frame section 22 includes a hub 40 upon which the wheel 16 is rotatably mounted. The four probes 18 extend radially from the outer perimeter of the wheel 16 and are spaced equally around the wheel at 90° intervals. A plurality of spikes 42 extend radially outwardly from the perimeter of the wheel 16, and are spaced at 90° intervals around the wheel between the probes 18. When the wheel 16 is in a ground engaging use position, the probes 16 and spikes 42 penetrate the ground and cause the wheel 16 to rotate as the truck 14 moves forwardly. The probes 18 are hollow tubes, and preferably include a longitudinally extending slot 44, which facilitates receipt and discharge of soil samples from the probes 18.

A plurality of plunger assemblies 46 are pivotally mounted on the inner face of the wheel 16, as best seen in Figure 3. Each of the plunger assemblies 46 is associated with one of the probes 16. Each plunger assembly 46 includes an arm 48 having a first end 50 having a tubular collar 52 welded thereto in a transverse relationship to the longitudinal axis of the arm 48. A bolt 54 extends through the wheel 16, the collar 52, and a tab 56 extending inwardly from the perimeter of the wheel 16. The bolt 54 defines a pivot axis for the outer end 50 of the arm 48.

Each plunger assembly also includes a rod 58. The inner end of the rod 58 is pivotally connected to the inner end 60 of the arm 48. The inner end of the rod 58 is connected to a

transverse collar 57 received within a cut out in the square tubular arm 48 and is pivotally secured in place with a nut and bolt assembly 61, as best seen in Figure 5. The outer end of the rod 58 has an enlarged head 59 and is adapted to slide within the hollow probe 18 so as to discharge the soil sample collected by the probe 18 during each rotation of the wheel 16. The extension of the rod 58 into the probe 18 is accomplished by a cam wheel 62 which engages the arm 48 after the probe 18 is withdrawn from the soil. As best seen in Figure 3, the cam wheel 62 engages the arm 48 at approximately a two o'clock position. As the clockwise rotation of the wheel 16 continues, the cam wheel 62 causes the arm 48 to pivot in a clockwise direction (as seen in Figure 3) about the horizontal axis defined by the bolt 54, thereby extending the rod 58 into the probe 18 such that the head 59 pushes out the soil sample contained in the probe 18. After the inner end 60 of the arm 48 moves past the cam wheel 62, the rod 58 is automatically urged to the retracted position by a spring 64 connected between the wheel 16 and the arm 48. The cam wheel 62 is adjustably mounted on the second frame section 22 with a mounting bracket 66. The guide collar 67 is axially aligned with the probe 18 to guide the extension and retraction of the rod 58 relative to the probe 18.

The second frame section 62 also includes an anti-reverse mechanism 68 to prevent the wheel from rotating counterclockwise. More particularly, the anti-reverse mechanism 68 includes a bar 70 mounted on the second frame section 22 and extending upwardly therefrom. An arm 72 is pivotally mounted to the bar 70 and extends laterally or transversely. The arm 72 has one end 74 extending toward the wheel 16 a sufficient distance to engage the tab 56 on the wheel 16. The opposite end 76 of the arm 72 extends away

100863600-030102

from the wheel 16. The bar 70 includes a stop element 78 which prevents the arm 72 from rotating clockwise, as seen in Figure 5, beyond the transverse position. Upon the normal clockwise rotation of the wheel 16, the bottom edge of the tab 56 engages the arm 72 and rotates it downwardly against the bias of the spring 80. After the tab 56 passes beyond the arm 72, the spring 80 urges the arm 72 back to the transverse position shown in Figure 5. If the wheel starts to rotate counterclockwise, which may occur when it is raised from the ground engaging position. The arm 72 will engage the top edge of the tab 56 to prevent further counterclockwise rotation of the wheel. Otherwise, the retracted rod 58 below the cam wheel 62 would hit the cam wheel and be bent or damaged.

The soil probe 10 is transported to the field or soil sampling site by the truck 14 with the wheel 16 folded to the transport position, as seen in Figure 4. In the transport position, the wheel has been raised, by the extension of the hydraulic cylinder rod 28, such that the probes 18 do not engage the ground. The wheel 16 remains in the transport position due to the inclined orientation of the pivot axis defined by the bolt 34 and the weight of the wheel 16.

Upon arrival at the desired location, the lock pin 36 is removed from the yoke 32 and the wheel 16 is manually folded from the transport position to the use position. The hydraulic cylinder 30 is then actuated so as to retract the rod 28, thereby lowering the wheel so that the probes 18 and spikes 42 will be forced into the ground. The lock pin 36 is reinserted into the yoke 32 and through the aligned hole in the second frame section 22 to limit the lateral movement of the wheel 16 to a relatively small angular range, preferably between 10°-15°.

100863600-030102

The truck can then be driven forwardly such that the wheel 16 rolls upon the ground, with each probe 18 collecting a soil sample as it is inserted into and withdrawn from the ground. As the rotation of the wheel 16 continues, the cam wheel 62 engages the lever arm 48 to extend the plunger rod 58 into the associated probe 18 to expel the soil sample from the outer end of the probe 18. Preferably, the probes 18 include a longitudinal slot which facilitates collection and discharge of the soil sample from the probe 18. An assistant riding in the back of the truck 14 collects the soil samples in any desired container as the sample is expelled from the probe 18 by the extended plunger rod 58. As the lever arm passes beyond the cam wheel 62, the spring 64 retracts the rod 58 so that the probe is ready to collect another soil sample.

Whereas the invention has been shown and described in connection with the preferred embodiment thereof, it will be understood that any modifications, substitutions, and additions may be made which are within the intended broad scope of the following claims. From the foregoing, it can be seen that the present invention accomplishes at least all of the stated objectives.